

Solution to Homework Assignment No. 1

1. (a) We can perform Gaussian elimination as follows:

$$\left[\begin{array}{ccc|c} 1 & 2 & 3 & 3 \\ 2 & 3 & 4 & 4 \\ 3 & 5 & 8 & 9 \end{array} \right] \Rightarrow \left[\begin{array}{ccc|c} 1 & 2 & 3 & 3 \\ 0 & -1 & -2 & -2 \\ 0 & -1 & -1 & 0 \end{array} \right] \Rightarrow \left[\begin{array}{ccc|c} 1 & 2 & 3 & 3 \\ 0 & -1 & -2 & -2 \\ 0 & 0 & 1 & 2 \end{array} \right].$$

Hence the pivots are 1, -1 and 1, and by back substitution the solution is given by

$$\begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 1 \\ -2 \\ 2 \end{bmatrix}.$$

- (b) Let $\mathbf{U}\mathbf{x} = \mathbf{c}$ and $\mathbf{L}\mathbf{c} = \mathbf{b}$. First, we solve \mathbf{c} from $\mathbf{L}\mathbf{c} = \mathbf{b}$:

$$\begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} = \begin{bmatrix} 4 \\ 5 \\ 6 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} = \begin{bmatrix} 4 \\ 1 \\ 1 \end{bmatrix}.$$

Next, we solve \mathbf{x} from $\mathbf{U}\mathbf{x} = \mathbf{c}$:

$$\begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 4 \\ 1 \\ 1 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 3 \\ 0 \\ 1 \end{bmatrix}.$$

2. (a) If \mathbf{A} is invertible, we have $\mathbf{A}\mathbf{A}^{-1} = \mathbf{I}$ and $\mathbf{A}^{-1}\mathbf{A} = \mathbf{I}$. Since we have $\mathbf{A}^2 = \mathbf{A}\mathbf{A}$ and $(\mathbf{A}^{-1})^2 = \mathbf{A}^{-1}\mathbf{A}^{-1}$, we can have

$$\begin{aligned} \mathbf{A}^2 (\mathbf{A}^{-1})^2 &= \mathbf{A} (\mathbf{A}\mathbf{A}^{-1}) \mathbf{A}^{-1} = \mathbf{A}\mathbf{I}\mathbf{A}^{-1} = \mathbf{A}\mathbf{A}^{-1} = \mathbf{I} \\ (\mathbf{A}^{-1})^2 \mathbf{A}^2 &= \mathbf{A}^{-1} (\mathbf{A}^{-1}\mathbf{A}) \mathbf{A} = \mathbf{A}^{-1}\mathbf{I}\mathbf{A} = \mathbf{A}^{-1}\mathbf{A} = \mathbf{I}. \end{aligned}$$

Hence \mathbf{A}^2 is invertible and $(\mathbf{A}^2)^{-1} = (\mathbf{A}^{-1})^2$.

- (b) For $m = 1$, the statement is obviously true. Assume $m = k$ is true. Then considering $m = k + 1$, we can have

$$\begin{aligned}\mathbf{A}^{k+1} (\mathbf{A}^{-1})^{k+1} &= \mathbf{A}^k (\mathbf{A}\mathbf{A}^{-1}) (\mathbf{A}^{-1})^k = \mathbf{A}^k \mathbf{I} (\mathbf{A}^{-1})^k = \mathbf{A}^k (\mathbf{A}^{-1})^k = \mathbf{I} \\ (\mathbf{A}^{-1})^{k+1} \mathbf{A}^{k+1} &= (\mathbf{A}^{-1})^k (\mathbf{A}^{-1}\mathbf{A}) \mathbf{A}^k = (\mathbf{A}^{-1})^k \mathbf{I} \mathbf{A}^k = (\mathbf{A}^{-1})^k \mathbf{A}^k = \mathbf{I}.\end{aligned}$$

Hence the statement holds for $m = k + 1$. By induction, this statement is true.

3. (a) By applying Gaussian-Jordan elimination, we have

$$\left[\begin{array}{cccc|cccc} 1 & -a & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 1 & -b & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & -c & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 \end{array} \right] \Rightarrow \left[\begin{array}{cccc|cccc} 1 & 0 & 0 & 0 & 1 & a & ab & abc \\ 0 & 1 & 0 & 0 & 0 & 1 & b & bc \\ 0 & 0 & 1 & 0 & 0 & 0 & 1 & c \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 \end{array} \right].$$

Hence

$$\mathbf{A}^{-1} = \begin{bmatrix} 1 & a & ab & abc \\ 0 & 1 & b & bc \\ 0 & 0 & 1 & c \\ 0 & 0 & 0 & 1 \end{bmatrix}.$$

- (b) From (a), we can guess

$$\mathbf{A}^{-1} = \begin{bmatrix} 1 & a & ab & abc & abcd \\ 0 & 1 & b & bc & bcd \\ 0 & 0 & 1 & c & cd \\ 0 & 0 & 0 & 1 & d \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}.$$

This can be confirmed by multiplying them:

$$\begin{aligned}\mathbf{A}\mathbf{A}^{-1} &= \begin{bmatrix} 1 & -a & 0 & 0 & 0 \\ 0 & 1 & -b & 0 & 0 \\ 0 & 0 & 1 & -c & 0 \\ 0 & 0 & 0 & 1 & -d \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & a & ab & abc & abcd \\ 0 & 1 & b & bc & bcd \\ 0 & 0 & 1 & c & cd \\ 0 & 0 & 0 & 1 & d \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix} = \mathbf{I} \\ \mathbf{A}^{-1}\mathbf{A} &= \begin{bmatrix} 1 & a & ab & abc & abcd \\ 0 & 1 & b & bc & bcd \\ 0 & 0 & 1 & c & cd \\ 0 & 0 & 0 & 1 & d \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & -a & 0 & 0 & 0 \\ 0 & 1 & -b & 0 & 0 \\ 0 & 0 & 1 & -c & 0 \\ 0 & 0 & 0 & 1 & -d \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix} = \mathbf{I}.\end{aligned}$$

4. (a) False. A counterexample is $\begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$. Since it does not have a full set of pivots, it is not invertible.
 (b) True. One can check that

$$(\mathbf{A}\mathbf{B} + \mathbf{B}\mathbf{A})^T = (\mathbf{A}\mathbf{B})^T + (\mathbf{B}\mathbf{A})^T = \mathbf{B}^T \mathbf{A}^T + \mathbf{A}^T \mathbf{B}^T = \mathbf{B}\mathbf{A} + \mathbf{A}\mathbf{B} = \mathbf{A}\mathbf{B} + \mathbf{B}\mathbf{A}.$$

5. (a) Suppose \mathbf{A} is singular. By elimination we can assume that there is an invertible matrix \mathbf{M} such that a row of \mathbf{MA} is zero. Since $\mathbf{MAB} = \mathbf{MI} = \mathbf{M}$, a row of \mathbf{M} is zero, which reaches a contradiction because \mathbf{M} is invertible. Hence \mathbf{A} is nonsingular and thus invertible. We can therefore obtain $\mathbf{B} = (\mathbf{A}^{-1}\mathbf{A})\mathbf{B} = \mathbf{A}^{-1}(\mathbf{AB}) = \mathbf{A}^{-1}\mathbf{I} = \mathbf{A}^{-1}$.
- (b) Consider $\mathbf{A}^T\mathbf{C}^T = \mathbf{I}^T = \mathbf{I}$. From (a), we have that \mathbf{A}^T is invertible and $(\mathbf{A}^T)^{-1} = \mathbf{C}^T$. Since $(\mathbf{A}^T)^{-1} = (\mathbf{A}^{-1})^T = \mathbf{C}^T$, we can obtain $\mathbf{A}^{-1} = \mathbf{C}$.
6. (a) Performing elimination, we can have

$$\mathbf{A} = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 3 \\ 1 & 3 & 6 \end{bmatrix} \xrightarrow{\mathbf{E}_{21}} \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 2 \\ 1 & 3 & 6 \end{bmatrix} \xrightarrow{\mathbf{E}_{31}} \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 2 \\ 0 & 2 & 5 \end{bmatrix} \xrightarrow{\mathbf{E}_{32}} \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{bmatrix} = \mathbf{U}.$$

This procedure can be viewed as

$$\mathbf{E}_{32}\mathbf{E}_{31}\mathbf{E}_{21}\mathbf{A} = \mathbf{U}$$

where

$$\mathbf{E}_{21} = \begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}, \quad \mathbf{E}_{31} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -1 & 0 & 1 \end{bmatrix}, \quad \text{and} \quad \mathbf{E}_{32} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -2 & 1 \end{bmatrix}.$$

Recording the elimination steps and changing the signs of the off-diagonal elements, we can have

$$\mathbf{L} = \mathbf{E}_{21}^{-1}\mathbf{E}_{31}^{-1}\mathbf{E}_{32}^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 1 & 2 & 1 \end{bmatrix}.$$

We also find that $\mathbf{U} = \mathbf{DL}^T$ where

$$\mathbf{D} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}.$$

We can therefore obtain $\mathbf{A} = \mathbf{LDL}^T$ as

$$\begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 3 \\ 1 & 3 & 6 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 1 & 2 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{bmatrix}.$$

- (b) Performing elimination, we can have

$$\mathbf{A} = \begin{bmatrix} 1 & 2 & 0 & 0 \\ 2 & 3 & 1 & 0 \\ 0 & 1 & 2 & 3 \\ 0 & 0 & 3 & 4 \end{bmatrix} \xrightarrow{\mathbf{E}_{21}} \begin{bmatrix} 1 & 2 & 0 & 0 \\ 0 & -1 & 1 & 0 \\ 0 & 1 & 2 & 3 \\ 0 & 0 & 3 & 4 \end{bmatrix} \xrightarrow{\mathbf{E}_{32}} \begin{bmatrix} 1 & 2 & 0 & 0 \\ 0 & -1 & 1 & 0 \\ 0 & 0 & 3 & 3 \\ 0 & 0 & 3 & 4 \end{bmatrix} \xrightarrow{\mathbf{E}_{43}} \begin{bmatrix} 1 & 2 & 0 & 0 \\ 0 & -1 & 1 & 0 \\ 0 & 0 & 3 & 3 \\ 0 & 0 & 0 & 1 \end{bmatrix} = \mathbf{U}.$$

This procedure can be viewed as

$$\mathbf{E}_{43}\mathbf{E}_{32}\mathbf{E}_{21}\mathbf{A} = \mathbf{U}$$

where

$$\mathbf{E}_{21} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ -2 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}, \mathbf{E}_{32} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}, \text{ and } \mathbf{E}_{43} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & -1 & 1 \end{bmatrix}.$$

Recording the elimination steps and changing the signs of the off-diagonal elements, we can have

$$\mathbf{L} = \mathbf{E}_{21}^{-1} \mathbf{E}_{32}^{-1} \mathbf{E}_{43}^{-1} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 2 & 1 & 0 & 0 \\ 0 & -1 & 1 & 0 \\ 0 & 0 & 1 & 1 \end{bmatrix}.$$

We also find that $\mathbf{U} = \mathbf{DL}^T$ where

$$\mathbf{D} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & 3 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}.$$

We can therefore obtain $\mathbf{A} = \mathbf{LDL}^T$ as

$$\begin{bmatrix} 1 & 2 & 0 & 0 \\ 2 & 3 & 1 & 0 \\ 0 & 1 & 2 & 3 \\ 0 & 0 & 3 & 4 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 2 & 1 & 0 & 0 \\ 0 & -1 & 1 & 0 \\ 0 & 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & 3 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 & 0 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 1 \end{bmatrix}.$$

7. (a) By (i), \mathbf{L}_1^{-1} and \mathbf{U}_2^{-1} both exist. Given $\mathbf{A} = \mathbf{L}_1 \mathbf{D}_1 \mathbf{U}_1$ and $\mathbf{A} = \mathbf{L}_2 \mathbf{D}_2 \mathbf{U}_2$, we can have

$$\begin{aligned} \mathbf{L}_2 \mathbf{D}_2 \mathbf{U}_2 &= \mathbf{L}_1 \mathbf{D}_1 \mathbf{U}_1 \\ \implies \mathbf{L}_1^{-1} (\mathbf{L}_2 \mathbf{D}_2 \mathbf{U}_2) \mathbf{U}_2^{-1} &= \mathbf{L}_1^{-1} (\mathbf{L}_1 \mathbf{D}_1 \mathbf{U}_1) \mathbf{U}_2^{-1} \\ \implies \mathbf{L}_1^{-1} \mathbf{L}_2 \mathbf{D}_2 &= \mathbf{D}_1 \mathbf{U}_1 \mathbf{U}_2^{-1}. \end{aligned}$$

By (i), \mathbf{L}_1^{-1} is lower triangular with unit diagonal. By (ii), $\mathbf{L}_1^{-1} \mathbf{L}_2$ is lower triangular with unit diagonal. Therefore, by (iii), $\mathbf{L}_1^{-1} \mathbf{L}_2 \mathbf{D}_2$ is lower triangular. Similarly, $\mathbf{D}_1 \mathbf{U}_1 \mathbf{U}_2^{-1}$ is upper triangular.

- (b) Let $\mathbf{M} = \mathbf{L}_1^{-1} \mathbf{L}_2 \mathbf{D}_2 = \mathbf{D}_1 \mathbf{U}_1 \mathbf{U}_2^{-1}$. Then \mathbf{M} is both lower and upper triangular, which implies that \mathbf{M} is a diagonal matrix.
- (1) Since $\mathbf{U}_1 \mathbf{U}_2^{-1}$ has a unit diagonal, $\mathbf{M} = \mathbf{D}_1 \mathbf{U}_1 \mathbf{U}_2^{-1}$ has the same diagonal as \mathbf{D}_1 . It implies that $\mathbf{M} = \mathbf{D}_1$. Similarly, we can have $\mathbf{M} = \mathbf{D}_2$. Therefore, $\mathbf{D}_1 = \mathbf{D}_2$.
 - (2) For $\mathbf{M} = \mathbf{L}_1^{-1} \mathbf{L}_2 \mathbf{D}_2 = \mathbf{D}_2$, we have $\mathbf{L}_1^{-1} \mathbf{L}_2 = \mathbf{I}$. Since the inverse matrix is unique, we have $\mathbf{L}_2 = (\mathbf{L}_1^{-1})^{-1} = \mathbf{L}_1$.
 - (3) Similarly, for $\mathbf{M} = \mathbf{D}_1 \mathbf{U}_1 \mathbf{U}_2^{-1} = \mathbf{D}_1$, we have $\mathbf{U}_1 \mathbf{U}_2^{-1} = \mathbf{I}$. It then implies that $\mathbf{U}_1 = (\mathbf{U}_2^{-1})^{-1} = \mathbf{U}_2$.

8. (a) First do row exchange as

$$\mathbf{A} = \begin{bmatrix} 0 & 2 & 2 \\ 1 & 2 & 2 \\ 2 & 6 & 7 \end{bmatrix} \xrightarrow{\mathbf{P}_{21}} \begin{bmatrix} 1 & 2 & 2 \\ 0 & 2 & 2 \\ 2 & 6 & 7 \end{bmatrix} = \mathbf{PA}$$

and then perform elimination as

$$\begin{bmatrix} 1 & 2 & 2 \\ 0 & 2 & 2 \\ 2 & 6 & 7 \end{bmatrix} \xrightarrow{\mathbf{E}_{31}} \begin{bmatrix} 1 & 2 & 2 \\ 0 & 2 & 2 \\ 0 & 2 & 3 \end{bmatrix} \xrightarrow{\mathbf{E}_{32}} \begin{bmatrix} 1 & 2 & 2 \\ 0 & 2 & 2 \\ 0 & 0 & 1 \end{bmatrix} = \mathbf{U}.$$

Then we have

$$\mathbf{E}_{32}\mathbf{E}_{31}(\mathbf{PA}) = \mathbf{U}$$

where

$$\mathbf{P} = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}, \quad \mathbf{E}_{31} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -2 & 0 & 1 \end{bmatrix}, \quad \text{and} \quad \mathbf{E}_{32} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -1 & 1 \end{bmatrix}.$$

We can have

$$\mathbf{L} = \mathbf{E}_{31}^{-1}\mathbf{E}_{32}^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 2 & 1 & 1 \end{bmatrix}.$$

The factorization $\mathbf{PA} = \mathbf{LU}$ is hence given by

$$\begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 0 & 2 & 2 \\ 1 & 2 & 2 \\ 2 & 6 & 7 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 2 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 & 2 \\ 0 & 2 & 2 \\ 0 & 0 & 1 \end{bmatrix}.$$

(b) In order to factor \mathbf{A} into $\mathbf{A} = \mathbf{L}_1\mathbf{P}_1\mathbf{U}_1$, we first perform elimination as

$$\mathbf{A} = \begin{bmatrix} 0 & 2 & 2 \\ 1 & 2 & 2 \\ 2 & 6 & 7 \end{bmatrix} \xrightarrow{\mathbf{E}_{32}} \begin{bmatrix} 0 & 2 & 2 \\ 1 & 2 & 2 \\ 0 & 2 & 3 \end{bmatrix} \xrightarrow{\mathbf{E}_{31}} \begin{bmatrix} 0 & 2 & 2 \\ 1 & 2 & 2 \\ 0 & 0 & 1 \end{bmatrix}$$

and then do row exchange as

$$\begin{bmatrix} 0 & 2 & 2 \\ 1 & 2 & 2 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{\mathbf{P}_{21}} \begin{bmatrix} 1 & 2 & 2 \\ 0 & 2 & 2 \\ 0 & 0 & 1 \end{bmatrix} = \mathbf{U}_1.$$

Therefore,

$$\mathbf{U}_1 = \mathbf{P}_{21}\mathbf{E}_{31}\mathbf{E}_{32}\mathbf{A}$$

where

$$\mathbf{P}_{21} = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}, \quad \mathbf{E}_{31} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -1 & 0 & 1 \end{bmatrix}, \quad \text{and} \quad \mathbf{E}_{32} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -2 & 1 \end{bmatrix}.$$

Multiplying $\mathbf{E}_{32}^{-1}\mathbf{E}_{31}^{-1}\mathbf{P}_{21}^{-1}$ from the left to both sides, we can have

$$\mathbf{A} = \mathbf{E}_{32}^{-1}\mathbf{E}_{31}^{-1}\mathbf{P}_{21}^{-1}\mathbf{U}_1 = \mathbf{L}_1\mathbf{P}_1\mathbf{U}_1$$

where

$$\mathbf{P}_1 = \mathbf{P}_{21}^{-1} = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

and

$$\mathbf{L}_1 = \mathbf{E}_{32}^{-1}\mathbf{E}_{31}^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 1 & 2 & 1 \end{bmatrix}.$$

The factorization $\mathbf{A} = \mathbf{L}_1\mathbf{P}_1\mathbf{U}_1$ is hence given by

$$\begin{bmatrix} 0 & 2 & 2 \\ 1 & 2 & 2 \\ 2 & 6 & 7 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 1 & 2 & 1 \end{bmatrix} \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 & 2 \\ 0 & 2 & 2 \\ 0 & 0 & 1 \end{bmatrix}.$$