

Final Examination

7:00pm to 10:00pm, June 15, 2012

Problems for Solution:

1. (20%) True or false. (If it is true, prove it. Otherwise, explain why not or find a counterexample.)

(a) The eigenvalues of \mathbf{A} are the same as the eigenvalues of \mathbf{A}^T .

(b) The matrix \mathbf{A} is similar to the matrix \mathbf{B} , where

$$\mathbf{A} = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}, \quad \mathbf{B} = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}.$$

(c) The linear transformation $T : \mathcal{R}^3 \rightarrow \mathcal{R}^2$ defined by

$$T(v_1, v_2, v_3) = (v_1 + v_2 + v_3, v_1 + 2v_2 + 3v_3)$$

has an inverse.

(d) Given the linear operator T on \mathcal{R}^3 defined by

$$T\left(\begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix}\right) = \begin{bmatrix} 2v_1 - v_2 \\ -v_1 + 2v_2 - v_3 \\ -v_2 + 2v_3 \end{bmatrix}$$

there is an orthonormal basis for \mathcal{R}^3 such that the matrix representation for T in this basis is a diagonal matrix.

2. (10%) Determine if each of the following matrices is diagonalizable. If it is, find an invertible matrix \mathbf{S} and a diagonal matrix $\mathbf{\Lambda}$ such that $\mathbf{S}^{-1}\mathbf{A}\mathbf{S} = \mathbf{\Lambda}$. If it is not, find its Jordan form.

(a) $\mathbf{A} = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 4 & 0 \\ 1 & 0 & 2 \end{bmatrix}$.

(b) $\mathbf{A} = \begin{bmatrix} 3 & -1 & -2 \\ 2 & 0 & -2 \\ 2 & -1 & -1 \end{bmatrix}$.

3. (10%) Consider a sequence in which each number is the average of two previous numbers, i.e.,

$$G_{k+2} = \frac{1}{2} (G_{k+1} + G_k), \text{ for } k \geq 0.$$

Starting from $G_0 = 0$ and $G_1 = 1/2$, find a formula for G_k and compute its limit as $k \rightarrow \infty$.

4. (15%) Consider

$$\mathbf{A} = \begin{bmatrix} 4 & -1 \\ 5 & 4 \end{bmatrix}.$$

Let

$$\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}.$$

- (a) Is $\mathbf{x}^T \mathbf{A} \mathbf{x}$ always positive for every nonzero vector \mathbf{x} ? Why?
 (b) Define for every nonzero vector \mathbf{x}

$$R(\mathbf{x}) = \frac{\mathbf{x}^T \mathbf{A} \mathbf{x}}{\mathbf{x}^T \mathbf{x}}.$$

Find the maximum of $R(\mathbf{x})$, i.e., $\max_{\mathbf{x} \neq \mathbf{0}} R(\mathbf{x})$.

- (c) Find a vector \mathbf{x} that achieves the minimum of $R(\mathbf{x})$ (i.e., $\min_{\mathbf{x} \neq \mathbf{0}} R(\mathbf{x})$).

5. (15%) Prove each of the following statements.

- (a) If σ is a (nonzero) singular value of \mathbf{A} , then there exists a nonzero vector \mathbf{x} such that

$$\sigma = \frac{\|\mathbf{A} \mathbf{x}\|}{\|\mathbf{x}\|}.$$

- (b) If \mathbf{A} is an n by n symmetric matrix with eigenvalues $\lambda_1, \lambda_2, \dots, \lambda_n$, then the singular values of \mathbf{A} are $|\lambda_1|, |\lambda_2|, \dots, |\lambda_n|$.

- (c) Let \mathbf{A} be an n by n matrix. Then $\mathbf{A}^T \mathbf{A}$ is similar to $\mathbf{A} \mathbf{A}^T$. (*Hint*: Consider the singular value decomposition of \mathbf{A} .)

6. (10%) Consider the vector space M of all 2 by 2 real matrices. The transformation

$T : M \rightarrow M$ is defined by for every $\mathbf{X} = \begin{bmatrix} x_1 & x_2 \\ x_3 & x_4 \end{bmatrix} \in M$ by

$$T(\mathbf{X}) = \mathbf{A} \mathbf{X}$$

where

$$\mathbf{A} = \begin{bmatrix} a & b \\ c & d \end{bmatrix}.$$

- (a) Show that T is linear.

(b) In class we know that $\beta = \{\mathbf{V}_1, \mathbf{V}_2, \mathbf{V}_3, \mathbf{V}_4\}$ form a basis for M , where

$$\mathbf{V}_1 = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \mathbf{V}_2 = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \mathbf{V}_3 = \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, \mathbf{V}_4 = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}.$$

Find the matrix representation for T (which is a 4 by 4 matrix) in this basis β .

7. (20%) Consider

$$\mathbf{A} = \begin{bmatrix} 1 & 1 \\ 0 & 0 \\ 1 & -1 \end{bmatrix}.$$

- (a) Find the pseudoinverse of \mathbf{A} .
- (b) Is there a left inverse for \mathbf{A} ? If yes, find one.
- (c) Find the projection matrix onto the column space of \mathbf{A} .
- (d) Given

$$\mathbf{b} = \begin{bmatrix} 3 \\ 5 \\ 5 \end{bmatrix}$$

there exist \mathbf{p} in the column space of \mathbf{A} and \mathbf{e} in the left nullspace of \mathbf{A} such that $\mathbf{b} = \mathbf{p} + \mathbf{e}$. Find the vector \mathbf{x}_r in the row space of \mathbf{A} such that $\mathbf{A}\mathbf{x}_r = \mathbf{p}$.