

Solution to Midterm Examination No. 1

1. (a) First, we solve \mathbf{c} from $\mathbf{Lc} = \mathbf{b}$:

$$\begin{bmatrix} 1 & 0 & 0 \\ 4 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \implies \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}.$$

Next, we solve \mathbf{x} from $\mathbf{Ux} = \mathbf{c}$:

$$\begin{bmatrix} 2 & 2 & 4 \\ 0 & 1 & 3 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \implies \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 1 \\ -3 \\ 1 \end{bmatrix}.$$

- (b) Yes, \mathbf{A} is invertible because it has a full set of pivots. Let the third column of \mathbf{A}^{-1} be $\hat{\mathbf{x}}$. Since $\mathbf{A}\hat{\mathbf{x}} = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$ which is the same system as that in (a), we can have $\hat{\mathbf{x}} = \mathbf{x} = \begin{bmatrix} 1 \\ -3 \\ 1 \end{bmatrix}$.

2. First do row exchange as

$$\mathbf{A} = \begin{bmatrix} -1 & 1 & 0 & 0 \\ 0 & 0 & 1 & -1 \\ 2 & -3 & 2 & -2 \\ -1 & 2 & -2 & 1 \end{bmatrix} \xrightarrow{\mathbf{P}_{32}} \begin{bmatrix} -1 & 1 & 0 & 0 \\ 2 & -3 & 2 & -2 \\ 0 & 0 & 1 & -1 \\ -1 & 2 & -2 & 1 \end{bmatrix} = \mathbf{PA}$$

and then perform elimination as

$$\begin{bmatrix} -1 & 1 & 0 & 0 \\ 2 & -3 & 2 & -2 \\ 0 & 0 & 1 & -1 \\ -1 & 2 & -2 & 1 \end{bmatrix} \xrightarrow{\mathbf{E}_{41}\mathbf{E}_{21}} \begin{bmatrix} -1 & 1 & 0 & 0 \\ 0 & -1 & 2 & -2 \\ 0 & 0 & 1 & -1 \\ 0 & 1 & -2 & 1 \end{bmatrix}$$

$$\xrightarrow{\mathbf{E}_{42}} \begin{bmatrix} -1 & 1 & 0 & 0 \\ 0 & -1 & 2 & -2 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & -1 \end{bmatrix} = \begin{bmatrix} -1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & -1 \end{bmatrix} \begin{bmatrix} 1 & -1 & 0 & 0 \\ 0 & 1 & -2 & 2 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & 1 \end{bmatrix} = \mathbf{DU}.$$

Then we have

$$\mathbf{E}_{42}\mathbf{E}_{41}\mathbf{E}_{21}(\mathbf{PA}) = \mathbf{U}$$

where

$$\mathbf{P} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$\mathbf{E}_{21} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 2 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}, \quad \mathbf{E}_{41} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ -1 & 0 & 0 & 1 \end{bmatrix}, \quad \text{and } \mathbf{E}_{42} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \end{bmatrix}.$$

We can have

$$\mathbf{L} = \mathbf{E}_{21}^{-1} \mathbf{E}_{41}^{-1} \mathbf{E}_{42}^{-1} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ -2 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 1 & -1 & 0 & 1 \end{bmatrix}.$$

The factorization $\mathbf{PA} = \mathbf{LDU}$ is hence given by

$$\begin{aligned} & \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} -1 & 1 & 0 & 0 \\ 0 & 0 & 1 & -1 \\ 2 & -3 & 2 & -2 \\ -1 & 2 & -2 & 1 \end{bmatrix} \\ &= \begin{bmatrix} 1 & 0 & 0 & 0 \\ -2 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 1 & -1 & 0 & 1 \end{bmatrix} \begin{bmatrix} -1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & -1 \end{bmatrix} \begin{bmatrix} 1 & -1 & 0 & 0 \\ 0 & 1 & -2 & 2 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & 1 \end{bmatrix}. \end{aligned}$$

3. (a) False. Let $\mathbf{C} = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$. Then

$$(\mathbf{I} + \mathbf{C})(\mathbf{I} - \mathbf{C}^T) = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ -1 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -1 & 1 \end{bmatrix}$$

is not a symmetric matrix.

- (b) True. Take $\mathbf{x}, \mathbf{y} \in S \cap T$ and hence $\mathbf{x}, \mathbf{y} \in S$, $\mathbf{x}, \mathbf{y} \in T$. We check the following two cases:

- (i) Consider $\mathbf{x} + \mathbf{y}$. Since $\mathbf{x} \in S$ and $\mathbf{y} \in S$, we have $\mathbf{x} + \mathbf{y} \in S$. Similarly, we can obtain $\mathbf{x} + \mathbf{y} \in T$. Hence $\mathbf{x} + \mathbf{y} \in S \cap T$.
- (ii) Consider $c\mathbf{x}$. Since $\mathbf{x} \in S$, we have $c\mathbf{x} \in S$. Similarly, we can have $c\mathbf{x} \in T$. Hence $c\mathbf{x} \in S \cap T$.

As a result, $S \cap T$ is a subspace of V .

(c) True. Consider $a\mathbf{y}_1 + b\mathbf{y}_2 + c\mathbf{y}_3 = \mathbf{0}$. We can have

$$a\mathbf{y}_1 + b\mathbf{y}_2 + c\mathbf{y}_3 = a\mathbf{A}\mathbf{x}_1 + b\mathbf{A}\mathbf{x}_2 + c\mathbf{A}\mathbf{x}_3 = \mathbf{A}(a\mathbf{x}_1 + b\mathbf{x}_2 + c\mathbf{x}_3) = \mathbf{0}.$$

Since \mathbf{A} is nonsingular, the only solution to the above system is

$$a\mathbf{x}_1 + b\mathbf{x}_2 + c\mathbf{x}_3 = \mathbf{0}.$$

As $\mathbf{x}_1, \mathbf{x}_2, \mathbf{x}_3$ are linearly independent, $a\mathbf{x}_1 + b\mathbf{x}_2 + c\mathbf{x}_3 = \mathbf{0}$ only if $a = b = c = 0$. Hence $\mathbf{y}_1, \mathbf{y}_2, \mathbf{y}_3$ are linearly independent.

4. (a) No. Let $V = \{3 \text{ by } 2 \text{ matrices with full column rank}\}$. Consider

$$\mathbf{w}_1 = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix}, \quad \mathbf{w}_2 = \begin{bmatrix} 0 & 1 \\ 1 & 0 \\ 0 & 0 \end{bmatrix} \in V.$$

Since

$$\mathbf{w}_1 + \mathbf{w}_2 = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix} + \begin{bmatrix} 0 & 1 \\ 1 & 0 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 1 & 1 \\ 0 & 0 \end{bmatrix} \notin V$$

V is not a subspace of M .

(b) Yes. Let

$$W = \left\{ \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \\ a_{31} & a_{32} \end{bmatrix} : a_{11} + a_{12} + a_{21} + a_{22} + a_{31} + a_{32} = 0 \right\}.$$

Suppose

$$\mathbf{w}_1 = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \\ a_{31} & a_{32} \end{bmatrix}, \quad \mathbf{w}_2 = \begin{bmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \\ b_{31} & b_{32} \end{bmatrix} \in W.$$

(i) Consider

$$\mathbf{w}_1 + \mathbf{w}_2 = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \\ a_{31} & a_{32} \end{bmatrix} + \begin{bmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \\ b_{31} & b_{32} \end{bmatrix} = \begin{bmatrix} a_{11} + b_{11} & a_{12} + b_{12} \\ a_{21} + b_{21} & a_{22} + b_{22} \\ a_{31} + b_{31} & a_{32} + b_{32} \end{bmatrix}.$$

Since

$$\begin{aligned} &(a_{11} + b_{11}) + (a_{12} + b_{12}) + (a_{21} + b_{21}) + (a_{22} + b_{22}) + (a_{31} + b_{31}) + (a_{32} + b_{32}) \\ &= (a_{11} + a_{12} + a_{21} + a_{22} + a_{31} + a_{32}) + (b_{11} + b_{12} + b_{21} + b_{22} + b_{31} + b_{32}) = 0 \end{aligned}$$

we have $\mathbf{w}_1 + \mathbf{w}_2 \in W$.

(ii) Consider

$$c\mathbf{w}_1 = \begin{bmatrix} ca_{11} & ca_{12} \\ ca_{21} & ca_{22} \\ ca_{31} & ca_{32} \end{bmatrix}.$$

Since

$$\begin{aligned} & ca_{11} + ca_{12} + ca_{21} + ca_{22} + ca_{31} + ca_{32} \\ &= c(a_{11} + a_{12} + a_{21} + a_{22} + a_{31} + a_{32}) = 0 \end{aligned}$$

we have $c\mathbf{w}_1 \in W$.

Hence M is a subspace of M . Since $a_{32} = -a_{11} - a_{12} - a_{21} - a_{22} - a_{31}$ we can have

$$\begin{aligned} \mathbf{w}_1 &= \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \\ a_{31} & -a_{11} - a_{12} - a_{21} - a_{22} - a_{31} \end{bmatrix} \\ &= a_{11} \begin{bmatrix} 1 & 0 \\ 0 & 0 \\ 0 & -1 \end{bmatrix} + a_{12} \begin{bmatrix} 0 & 1 \\ 0 & 0 \\ 0 & -1 \end{bmatrix} + a_{21} \begin{bmatrix} 0 & 0 \\ 1 & 0 \\ 0 & -1 \end{bmatrix} + a_{22} \begin{bmatrix} 0 & 0 \\ 0 & 1 \\ 0 & -1 \end{bmatrix} + a_{31} \begin{bmatrix} 0 & 0 \\ 0 & 0 \\ 1 & -1 \end{bmatrix}. \end{aligned}$$

One can check that

$$\left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \\ 0 & -1 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \\ 0 & -1 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 0 \\ 0 & -1 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \\ 0 & -1 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 0 \\ 1 & -1 \end{bmatrix} \right\}$$

is a basis for W , and hence the dimension of W is 5.

5. (a) We can know that \mathbf{A} must be 2 by 3. Since $\mathbf{x} = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$ is the only solution to

$\mathbf{A}\mathbf{x} = \begin{bmatrix} 1 \\ -2 \end{bmatrix}$, the nullspace of \mathbf{A} must contain the zero vector only. Hence the rank of \mathbf{A} should be 3. Yet as the number of rows of \mathbf{A} is only 2, the rank of \mathbf{A} cannot be 3. Therefore, \mathbf{A} does not exist.

(b) Since $\mathbf{A}\mathbf{x} = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$ has exactly one solution, the nullspace of \mathbf{A} must contain the zero vector only. Hence \mathbf{A} is a matrix with full column rank. And since

$\mathbf{A}\mathbf{x} = \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$ has no solution, the third equation corresponding to the RRE

form of $\left[\mathbf{A} \begin{array}{c} 1 \\ 2 \\ 1 \end{array} \right]$ should be inconsistent. One example of \mathbf{A} is $\begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix}$.

6. (a) No. Since there are 4 vectors in \mathcal{R}^3 , they must be linearly dependent.

(b) No. Consider solving

$$a\mathbf{x}_1 + b\mathbf{x}_2 + c\mathbf{x}_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \implies \left[\begin{array}{ccc|c} 1 & 1 & 1 & 0 \\ 2 & 3 & 5 & 0 \\ 2 & 3 & 5 & 1 \end{array} \right] \implies \left[\begin{array}{ccc|c} 1 & 0 & -2 & 0 \\ 0 & 1 & 3 & 0 \\ 0 & 0 & 0 & 1 \end{array} \right].$$

Since the 3rd equation is inconsistent, this system is not solvable. Hence $\mathbf{x}_1, \mathbf{x}_2, \mathbf{x}_3$ do not span \mathcal{R}^3 .

(c) Yes. Consider $\mathbf{A} = [\mathbf{x}_1 \ \mathbf{x}_2 \ \mathbf{x}_4]$. Since the RRE form of \mathbf{A} is an identity matrix, \mathbf{A} has a full set of pivots and $\mathbf{x}_1, \mathbf{x}_2, \mathbf{x}_4$ are linearly independent. Hence $\mathbf{x}_1, \mathbf{x}_2, \mathbf{x}_4$ form a basis for \mathcal{R}^3 .

7. (a) We can obtain

$$\mathbf{A} = \begin{bmatrix} 1 & -4 & 2 & 5 \\ 3 & -12 & 6 & 15 \\ -2 & 8 & -4 & -10 \end{bmatrix} = \begin{bmatrix} 1 \\ 3 \\ -2 \end{bmatrix} [1 \ -4 \ 2 \ 5] = \mathbf{u}\mathbf{v}^T.$$

(b) The matrix \mathbf{A} is a rank-one matrix with pivot row $(1, -4, 2, 5)$. Therefore, a basis for the row space of \mathbf{A} is $(1, -4, 2, 5)$.

(c) Since $(1, 3, -2)^T$ is the pivot column of \mathbf{A} , for the left nullspace, we have

$$[y_1 \ y_2 \ y_3] \begin{bmatrix} 1 \\ 3 \\ -2 \end{bmatrix} = \mathbf{0}^T.$$

Therefore, a basis for the left nullspace of \mathbf{A} can be given by

$$(-3, 1, 0), (2, 0, 1).$$

8. (a) Since the permutation matrix \mathbf{P} does not change the order of the columns of \mathbf{A} , from \mathbf{U} we can find that the pivot columns of \mathbf{A} are the 1st, 3rd, and 5th columns. Hence a basis for the column space of \mathbf{A} can be given by

$$\begin{bmatrix} 0 \\ 2 \\ 4 \\ 2 \end{bmatrix}, \begin{bmatrix} 1 \\ 4 \\ 9 \\ 5 \end{bmatrix}, \begin{bmatrix} 2 \\ 1 \\ 4 \\ 5 \end{bmatrix}.$$

(b) False. Form the 1st, 2nd, and 4th rows of \mathbf{L} , we can find that the 1st, 2nd, and 4th rows of \mathbf{PA} are linearly dependent. Form \mathbf{P} , we also know that the 1st, 2nd, and 4th rows of \mathbf{PA} are equal to the 2nd, 1st, and 3rd rows of \mathbf{A} , respectively. Therefore, rows 1, 2, 3 of \mathbf{A} are linearly dependent.

(c) The nullspace of \mathbf{A} is equal to the nullspace of \mathbf{PA} . From \mathbf{U} , we know that x_1, x_3 , and x_5 are pivot variables and x_2 and x_4 are free variables. Therefore, the general solution to $\mathbf{Ax} = \mathbf{0}$ can be given by

$$x_2 \begin{bmatrix} 1/2 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} -7 \\ 0 \\ 3 \\ 1 \\ 0 \end{bmatrix}.$$